

Free Surface Deformation of the Weld Pool in Orbital Narrow Groove GTA Welding

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**COMSOL
CONFERENCE**
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- Case of application : **Gas Tungsten Arc Welding**
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Working with SIMTEC

Industry Challenges

- R&D sections: experts in their field
→ Expertise in numerical modelling?
- Lack of time
- FE modelling performed by a small group of people



SIMTEC's Solutions

- Numerical modelling project
→ SIMTEC's member as your colleague
→ Help improve your modelling knowledge!
→ Cost-effective outsourcing



Our team & Our clients

Numerical Modelling Consultants



6 Members all EngD + PhD

- Extensive research background
- Complex problems
- Various fields of expertise

Successful Track Record:

- Big international companies
- Government laboratories

Involved in Research Consortia

- EU funded projects (REEcover / SHARK)
- PhD projects supervision.



→ Discover more about our
successful modelling work
with clients!

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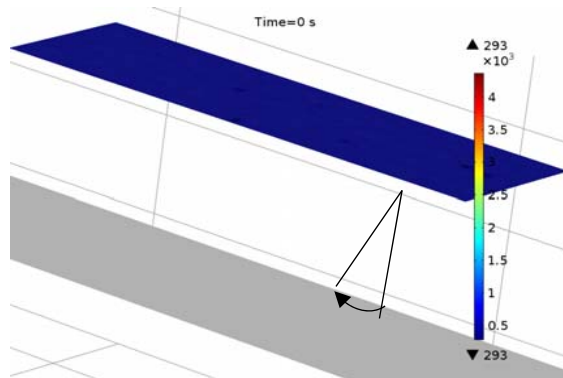
Assembly Process Modelling



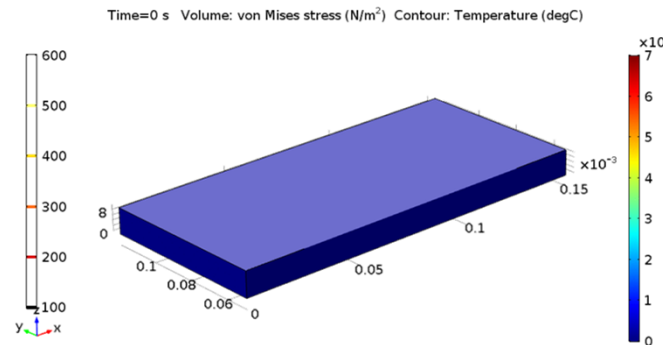
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SHARK
INDUSTRIALISING LASER
FUNCTIONAL TEXTURING

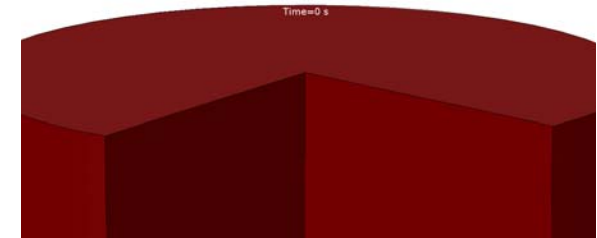
Continuous Laser Welding



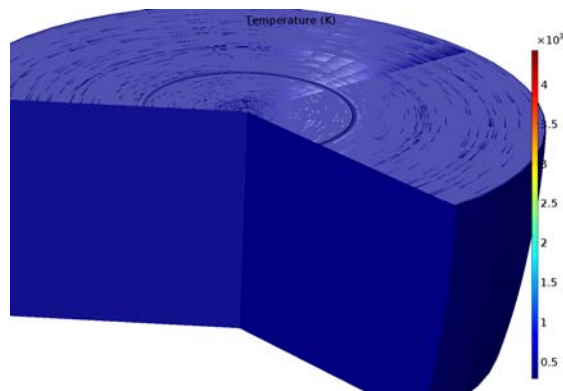
Additive Manufacturing



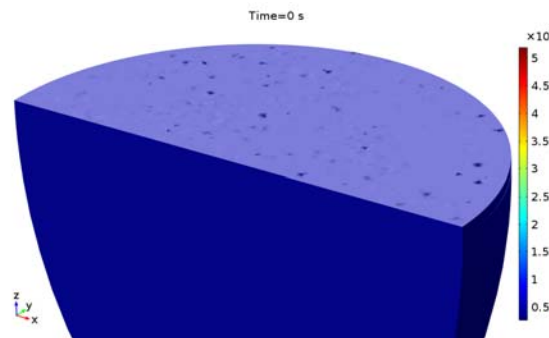
Laser Surface Texturing



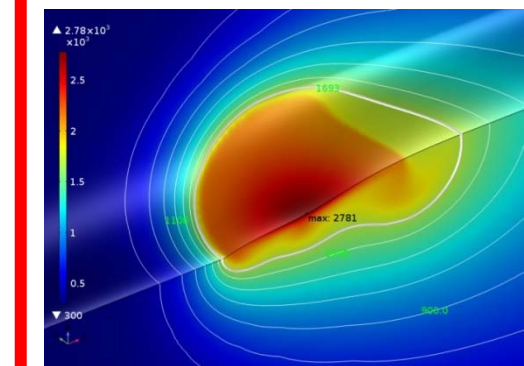
Laser Drilling



Heterogeneous Laser Welding

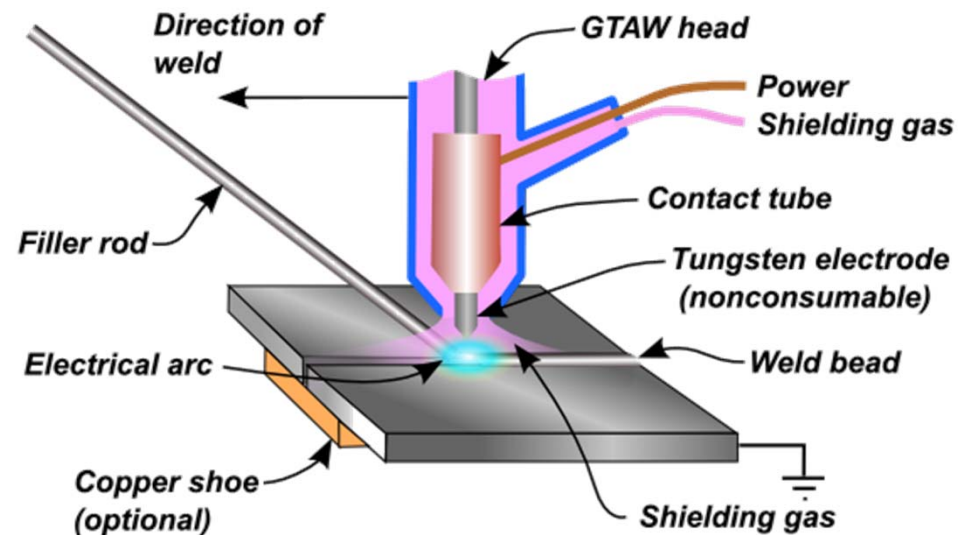


GTA Welding



Process Description and Objectives

Gas Tungsten Arc Welding (GTAW)



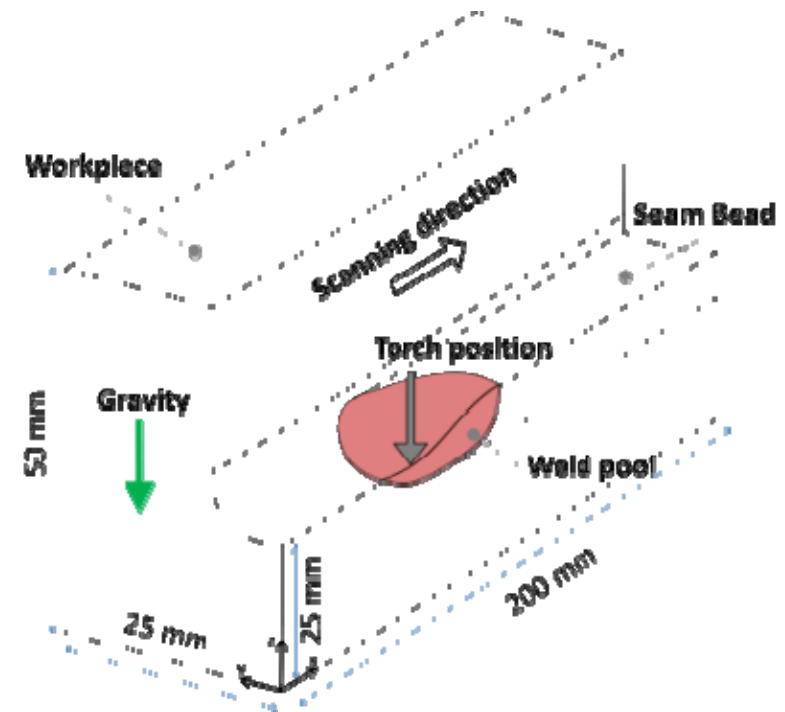
https://en.wikipedia.org/wiki/Gas_tungsten_arc_welding

- To **understand** the welding process behavior and the influence of all the process parameters
- To **predict** the dimensions of the Melted Zone, the Heat Affected Zone and the Weld Bead
- To **improve** the robustness of a welding application

Geometry and Materials

- Narrow Groove Welding
- 3D model
- One symmetry plane
- Material: 316L stainless steel

IAEA report, "Thermophysical properties of materials for nuclear engineering: a tutorial and collection of data" (2008)



Physical Phenomena & Modelling

Electro-Magnetism

$$\nabla \cdot (\sigma \nabla V) = 0$$

$$\nabla \times \left(\frac{1}{\mu_0} \nabla \times \mathbf{A} \right) + \sigma \nabla V = 0$$

Energy Balance

$$\rho C_p (\mathbf{u} - \mathbf{u}_{\text{weld}}) \cdot \nabla T = \nabla \cdot (k \nabla T) + Q_{EM}$$

Mass and Momentum Balances

$$\nabla \cdot (\mathbf{u}) = 0$$

$$\rho_L (\mathbf{u} \cdot \nabla) \mathbf{u} = \nabla \cdot \left(-p \mathbf{I} + \mu (\nabla \mathbf{u} + (\nabla \mathbf{u})^T) \right) + \mathbf{F}_{\text{Darcy}} + \mathbf{F}_{EM} + \mathbf{F}_{\text{Buoyancy}}$$

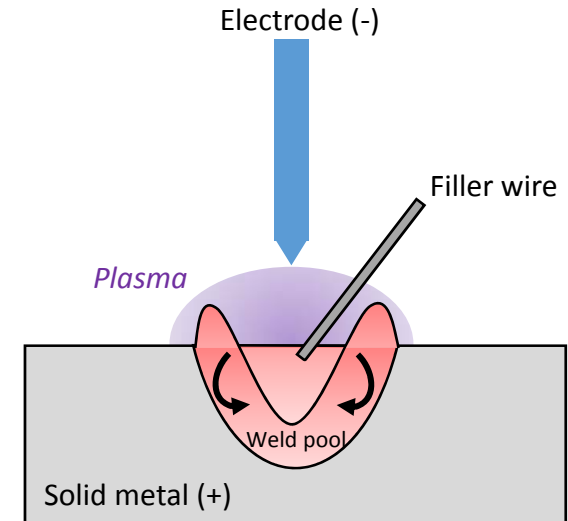
Free Surface Description

[1]

$$-\nabla \cdot \left(\frac{\gamma}{\sqrt{1 + \phi_x^2 + \phi_y^2}} \nabla \phi \right) = P_{\text{arc}} + \rho g + \lambda$$

Moving Mesh (Hyperelastic)

$$W = \int_{\Omega} \frac{\eta}{2} (I_1 - 3) + \frac{\kappa}{2} (J - 1)^2 dV$$



Mechanisms

Joule Heating
Lorentz Force

Liquid/solid transition
Evaporation
Buoyancy
Marangoni effects

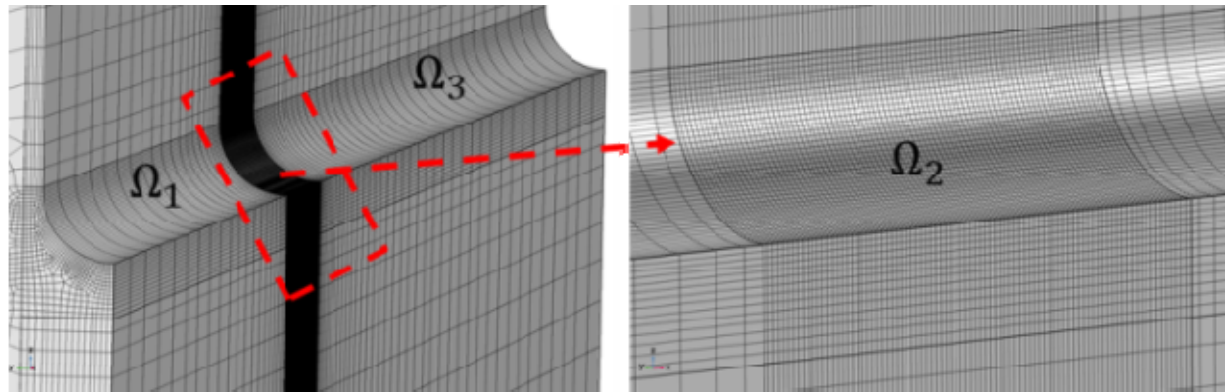
Gravity
Surface tension
Arc pressure

Filler Metal 8

[1] Wu et al., Numerical analysis of both front-and back-side deformation of fully penetrated GTAW weld pool surfaces, *Computational Materials Science*, **39**, 635-642 (2007)

Numerical Aspects

- Fine and mapped mesh



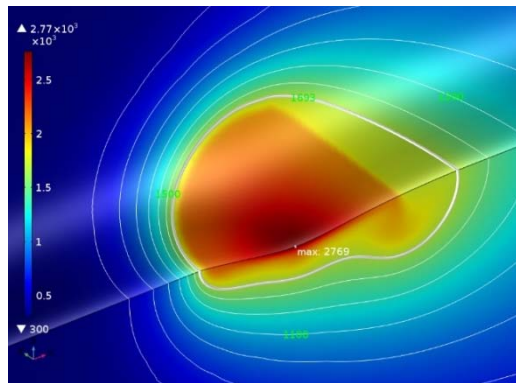
- Strong couplings (multi-physics) and highly non-linear problem
 - **Adapted solving strategy**
 - Each equation is firstly solved separately
 - Thermo-hydraulic problem is then solved in the new configuration
 - The segregated solver is lastly used to solve the whole problem
- \cong 1 million of DoF → 10 hours with 6 cores and 192 Go RAM

Results

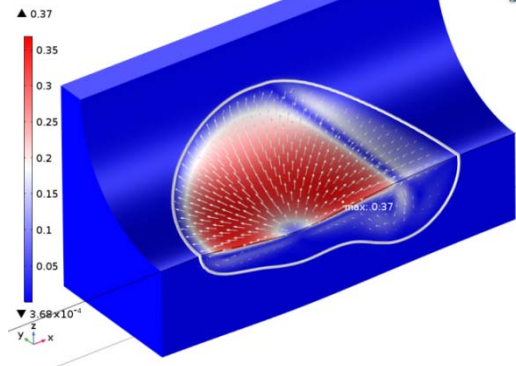
Influence of the filler metal

without filler metal

$T [K]$

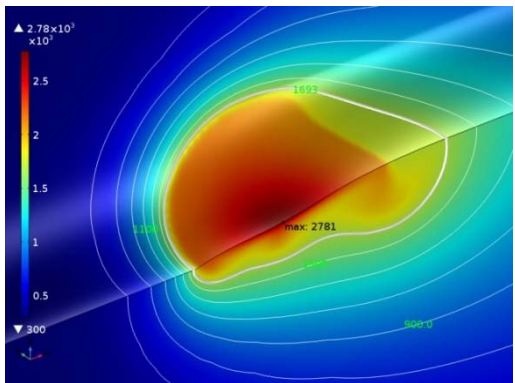


$u [m/s]$

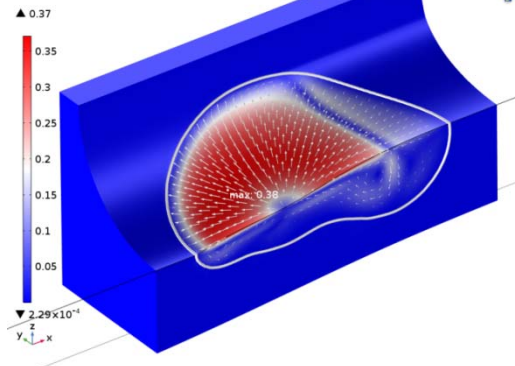


with filler metal

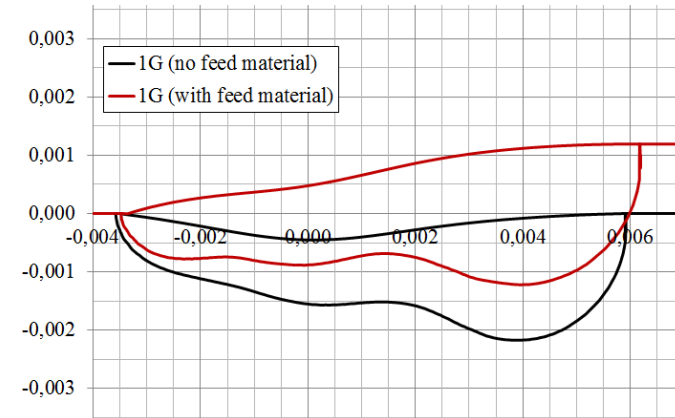
$T [K]$



$u [m/s]$



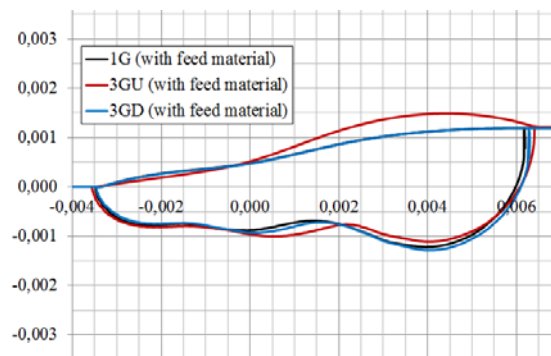
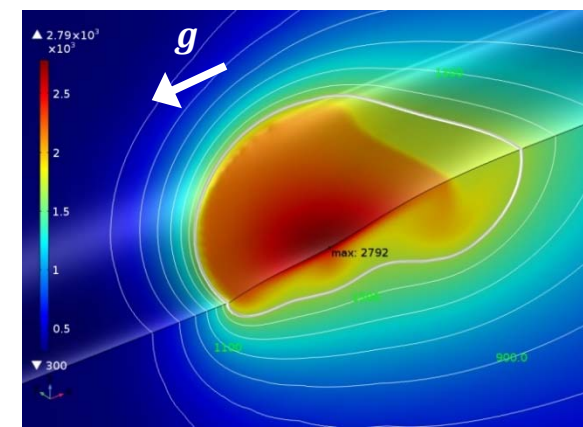
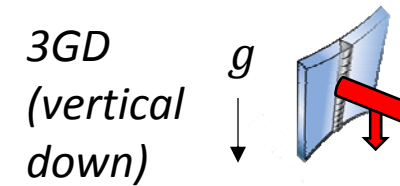
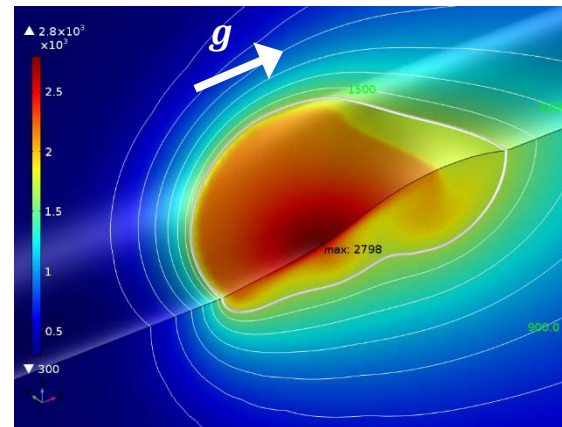
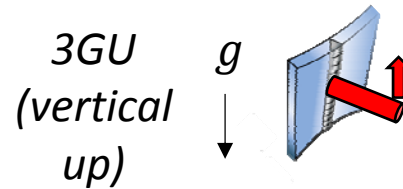
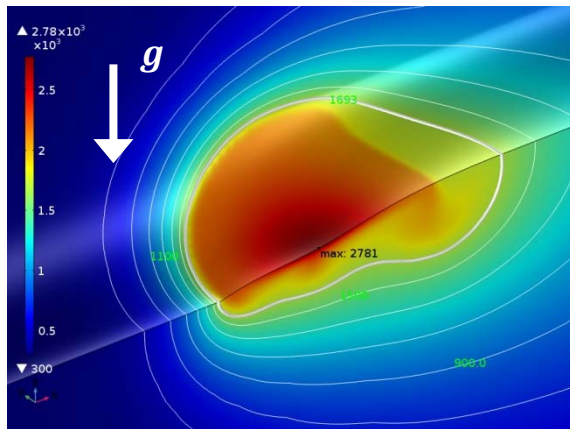
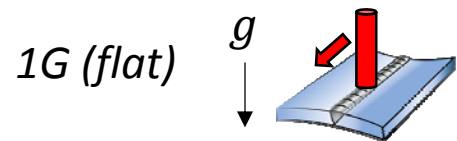
Comparison of cross-sections



- **Convective cells** with contrary rotation making the **melt pool deeper at the rear** than under the welding torch
- **Little impact** of the filler metal on the **velocities and Temperature maximum**
- **Melt pool volume** remains the same for both configurations
- **Penetration depth decreases** for the case **with filler metal** and **creation of a weld bead**

Results

Influence of the welding position

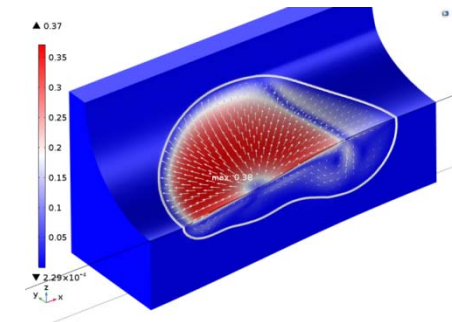
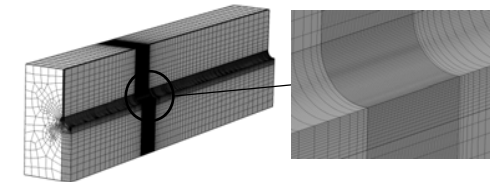
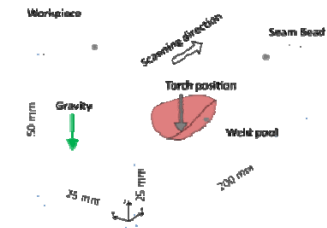


- 1G and 3GD show little difference
- 3GU shows a larger deformation at the back of the pool → **effect of the heavy liquid metal**
- **Limited sensitivity to the welding position**

Summary & Future Work

- **3D Multiphysics Model** applied to GTA Welding and taking into account several physical phenomena on **an industrial application geometry**
- **Numerical aspects** carefully managed to obtain stationary state convergence
- **Numerical trends** in agreement with literature data
- Comparison in progress with **experimental data**

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Thanks for your attention .. and your questions!



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Results

Influence of the filler metal

